

Physics 212 - Problem Set # 7

Solutions

1.) a.) Begin from

$$G = \int d^3x \left\{ \frac{1}{2m} |\vec{D}\Phi|^2 + \frac{1}{2} a (T - T_c) |\Phi|^2 + \frac{b}{4} |\Phi|^4 \right\}$$

where $\vec{D} = \vec{\nabla} - i \frac{eQ}{c} \vec{A}$

For Φ constant, $\vec{A} = 0$, the minimum of G is given by

$$0 = \frac{\partial G}{\partial \Phi^*} \left\{ \frac{1}{2} a (T - T_c) |\Phi|^2 + \frac{b}{4} |\Phi|^4 \right\}$$

$$= \frac{1}{2} a (T - T_c) \Phi + \frac{b}{2} \Phi |\Phi|^2$$

$$\Rightarrow |\Phi|^2 = \frac{a(T - T_c)}{b} \quad \Phi = \Phi_0 = \left[\frac{a(T_c - T)}{b} \right]^{\frac{1}{2}}$$

We can choose a gauge where Φ is real. Then, still with $\vec{A} = 0$

$$\Phi(x) = \Phi_0 + \delta\Phi(x)$$

$$G \approx (\text{const}) + \int d^3x \left\{ \frac{1}{2m} |\vec{\nabla}\Phi|^2 + \frac{1}{2} a (T - T_c) (\Phi_0 + \delta\Phi)^2 + \frac{b}{4} (\Phi_0 + \delta\Phi)^4 \right\}$$

$$= (\text{const}) + \int d^3x \left\{ \delta\Phi^* \left(-\frac{1}{2m} \nabla^2 \right) \delta\Phi + \frac{1}{2} a (T - T_c) 2\Phi_0 \delta\Phi + \delta\Phi^2 + \frac{b}{4} (4\Phi_0^3 \delta\Phi + 6\Phi_0^2 \delta\Phi^2 + \dots) \right\}$$

The terms linear in $\delta\Phi$ are

$$(a(T - T_c) \Phi_0 + b \Phi_0^3) \delta\Phi = 0 \quad \text{with } \Phi_0 \text{ as above}$$

the quadratic term are

$$\begin{aligned}
 C &= \int d^3x \left\{ \delta\Phi \left(-\frac{1}{2m} \nabla^2 \right) \delta\Phi + \frac{1}{2} a (T_c - T) \delta\Phi^2 + \frac{6}{4} b \Phi_0^2 \delta\Phi^2 \right\} \\
 &= \int d^3x \delta\Phi \left\{ -\frac{1}{2m} \nabla^2 + \left(\frac{3}{2} b \frac{a(T_c - T)}{b} - \frac{1}{2} a (T_c - T) \right) \right\} \delta\Phi \\
 &= \int d^3x \frac{1}{2m} \delta\Phi \left[-\nabla^2 + 2ma(T_c - T) \right] \delta\Phi
 \end{aligned}$$

The resulting Green's function satisfies

$$\left[-\nabla^2 + 2ma(T_c - T) \right] G(x, y) = mT \delta(x - y)$$

and behaves as

$$G(x, y) \sim e^{-\kappa |x-y|} \xi$$

where $\xi = [2ma(T_c - T)]^{-1/2}$

b.) Now expand around $\bar{\Phi} = 0$. The first term are quadratic

$$C = \int d^3x \left[\frac{1}{2m} \Phi^\dagger (-D^2) \Phi - \frac{1}{2} a (T_c - T) \Phi^\dagger \Phi \right]$$

$$\vec{D} = \left(\vec{\nabla} - i \frac{eQ}{c} \mathbf{H} \times \hat{y} \right)$$

$$D^2 = \nabla^2 - 2i \frac{eQ}{c} \mathbf{H} \times \hat{y} \cdot \vec{\nabla} - \left(\frac{eQ}{c} H_x \right)^2$$

Then

$$\odot = -\frac{1}{2m} \left(\nabla^2 - 2i \frac{eQ}{c} \mathbf{H} \times \hat{y} \cdot \vec{\nabla} - \left(\frac{eQ}{c} H_x \right)^2 \right) - \frac{1}{2} a (T_c - T)$$

The eigenvalue problem is

$$\odot \Phi(x) = \lambda \Phi(x)$$

c.) Act $\mathcal{O}(H)$ on $\Phi(x, y, z) = e^{ik_y y} e^{ik_z z} f(x)$

$$\begin{aligned} \mathcal{O}\Phi &= \left[-\frac{1}{2m} \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} - 2i \frac{eQ}{c} H x \frac{\partial}{\partial y} - \left(\frac{eQ}{c} H x \right)^2 + \frac{\partial^2}{\partial z^2} \right) \right. \\ &\quad \left. - \frac{1}{2} a (T_C - T) \right] \Phi \\ &= -\frac{1}{2m} \left[\frac{\partial^2}{\partial x^2} - k_y^2 + 2 \frac{eQ}{c} H x k_y - \left(\frac{eQ}{c} H x \right)^2 - k_z^2 \right] \\ &\quad - \frac{1}{2} a (T_C - T) \left] e^{ik_y y} e^{ik_z z} f(x) \end{aligned}$$

so the eigenvalue equation becomes,

$$\begin{aligned} \left\{ -\frac{1}{2m} \frac{\partial^2}{\partial x^2} + \frac{1}{2m} \left(\frac{eQ}{c} H x - k_y \right)^2 + \frac{k_z^2}{2m} - a (T_C - T) \right\} f(x) \\ = \lambda f(x) \end{aligned}$$

d.)

$$\begin{aligned} \left[-\frac{1}{2m} \frac{\partial^2}{\partial x^2} + \frac{1}{2m} \left(\frac{eQ}{c} H \right)^2 (x - x_0)^2 + \frac{k_z^2}{2m} - \frac{1}{2} a (T_C - T) \right] f(x) \\ = \lambda f(x) \end{aligned}$$

the first two terms can be written as

$$\Omega = \frac{eQH}{mc}$$

$$-\frac{1}{2m} \frac{\partial^2}{\partial x^2} + \frac{1}{2} m \Omega^2 (x - x_0)^2$$

$$x_0 = \frac{c}{eQH} k_y$$

which is the harmonic oscillator Hamiltonian. Its eigenvalues are

$$\Omega (n + \frac{1}{2})$$

so

$$\lambda = \Omega(n + \frac{1}{2}) + \frac{k_z^2}{2m} - \frac{1}{2}a(T_c - T)$$

e.) The limit eigenvalue occurs for $k_z = 0$ and $n = 0$

$$\begin{aligned} \lambda_0 &= \frac{1}{2}\Omega - \frac{1}{2}a(T_c - T) \\ &= \frac{1}{2} \frac{eQ}{mc} H - \frac{1}{2}a(T_c - T) \end{aligned}$$

f.) This eigenvalue passes through 0, signaling an instability, at

$$H_* = am(T_c - T) \cdot \frac{c}{eQ}$$

(As long as $\lambda_0 > 0$, the situation $\langle \Phi \rangle = 0$ at that H is stable.)

g.) We find for H_c

$$H_c = \left[\frac{2\pi a^2}{bc} \right]^{1/2} (T_c - T)$$

so

$$\frac{H_*}{H_c} = \frac{am(c/eQ)}{\left[\frac{2\pi a^2}{bc} \right]^{1/2}} = \frac{am}{\left[\frac{2\pi a^2}{bc} \left(\frac{eQ}{c} \right)^2 \right]^{1/2}}$$

h.) Now $\delta = \left[2am(T_c - T) \right]^{-1/2}$

and we find in class: $\lambda = \left[\frac{4\pi}{mc} \left(\frac{eQ}{c} \right)^2 \Phi_0^2 \right]^{-1/2}$

again:

$$\xi = [2am(T_c - T)]^{-1/2}$$

$$\lambda = \left[\frac{4\pi}{mc} \left(\frac{Qe}{c} \right)^2 \frac{a(T_c - T)}{b} \right]^{-1/2}$$

then

$$\frac{\lambda}{\xi} = \left[\frac{2am}{\frac{4\pi}{mc} \left(\frac{Qe}{c} \right)^2 \frac{a}{b}} \right]^{1/2}$$

$$= \left[\frac{2a^2m^2}{\frac{4\pi a^2}{bc} \left(\frac{Qe}{c} \right)^2} \right]^{1/2} = \left[\frac{am}{\frac{2\pi a^2}{bc} \left(\frac{Qe}{c} \right)^2} \right]^{1/2}$$

so

$$\frac{H_*}{H_c} = \frac{\lambda}{\xi} !$$

If $H_* > H_c$ there is an Abrikosov phase (Type II)
and otherwise not (Type I).