

Physics 210 – Problem Set # 4

(due Thursday, October 21)

1. Consider a system of particles of charge q and mass m which move in a uniform magnetic field \vec{B} .

(a) Show that this constant magnetic field is represented by the vector potential

$$\vec{A} = -\frac{1}{2}\vec{r} \times \vec{B} \quad (1)$$

(b) Write the Lagrangian for this system of particles. Show that the effect of \vec{B} is removed, to first order in \vec{B} , by working in a coordinate system which rotates with the angular velocity

$$\vec{\Omega}_L = -\frac{q}{2mc}\vec{B} \quad (2)$$

This result is called *Larmor's theorem*.

2. Let $(R_{\hat{n}}(\alpha))_{ij}$ be the 3×3 matrix which implements a rotation by α about the axis \hat{n} .

(a) Show that

$$\chi(\alpha) = \text{tr}[R_{\hat{n}}(\alpha)] = 1 + 2 \cos \alpha \quad (3)$$

This quantity is called the *character* of the rotation. To prove this relation, first consider a rotation about $\hat{n} = \hat{z}$, and then show that χ is independent of \hat{n} .

(b) Use this relation to compute the rotation angle α in terms of the Euler angles. Show that

$$\cos \frac{\alpha}{2} = \cos \frac{\phi + \psi}{2} \cos \frac{\theta}{2} \quad (4)$$

3. Consider a jet plane moving through the air at fixed speed v . Define a fixed coordinate system in the air by taking \hat{y} to point upward and \hat{z}, \hat{x} to be horizontal. We can also associate a coordinate system with the plane as follows: Let the $\hat{\zeta}$ axis point forward, let the $\hat{\xi}$ axis point toward the left wing, and let the $\hat{\eta}$ axis point up. Then we can describe the orientation of the jet with respect to the fixed coordinate system $(\hat{x}, \hat{y}, \hat{z})$ in terms of Euler angles.

(a) Assuming that the jet is always instantaneously moving forward, that is, in the $\hat{\zeta}$ direction, show that its velocity vector is

$$\vec{v} = v(\sin \theta \cos \phi, \sin \theta \sin \phi, \cos \theta) \quad (5)$$

- (b) Show that, with these coordinates, a banked turn is described by setting

$$\phi = 0, \quad \dot{\theta} = \omega, \quad \psi = (\text{const}) \quad (6)$$

with ω constant. If the initial velocity is in the \hat{z} direction, find the velocity and the position of the jet as a function of time.

- (c) The situation

$$\phi = (\text{const}), \quad \dot{\theta} = \omega, \quad \psi = 0 \quad (7)$$

leads to a different outcome. Find the velocity and position as a function of time in this case.

- (d) Now consider a situation in which the pilot maintains a fixed angular velocity

$$\vec{\Omega} = a\hat{\zeta} + b\hat{\eta} \quad (8)$$

relative to the jet. Convert this expression to three first-order differential equations for the Euler angles by considering the relation

$$\begin{aligned} \vec{\Omega} = \hat{\xi}[-\dot{\phi} \sin \theta \cos \psi + \dot{\theta} \sin \psi] + \hat{\eta}[\dot{\phi} \sin \theta \sin \psi + \dot{\theta} \cos \psi] \\ + \hat{\zeta}[\dot{\phi} \cos \theta + \dot{\psi}] \end{aligned} \quad (9)$$

and solving for $\dot{\theta}$, $\dot{\phi}$, $\dot{\psi}$.

- (e) Initially, $\theta = \phi = \psi = 0$. Analyze the equations for small t starting from this initial condition. Show that

$$\theta = bt, \quad \phi = \psi = \frac{1}{2}at, \quad (10)$$

to first order in t .

- (f) Since the equations obtained in part (d) are singular when $\theta, \psi = 0$, it is not completely straightforward to integrate them numerically from $t = 0$. To evade this problem, use the result of part (e) for small times, and integrate numerically starting from $t = \epsilon$ (with, for example, $\epsilon = 0.001$). Using this strategy, study the case $a = 1/\text{sec}$, $b = 2/\text{sec}$, and find the three Euler angles numerically as a function of time.
- (g) Now let $v = 500 \text{ km/sec}$. Find, numerically, the height of the jet relative to its original trajectory as a function of time. Follow the motion from 0 to 10 seconds.