

Theory of Relativity - 2

March 9

In the previous lecture, we considered the relation between coordinates (t, \vec{x}) measured in one inertial frame F and the corresponding coordinates (t', \vec{x}') measured in an inertial frame F' moving with respect to F with constant velocity $\vec{v} = v \hat{z}$. We found that this relation has many weird properties.

Let's now try to find the explicit relation by a general analysis. Here are some reasonable requirements that the transformation $(t, \vec{x}) \rightarrow (t', \vec{x}')$ should satisfy:

- ① $x = x'$ $y = y'$ (as we argued last time)
- ② (t', \vec{x}') should be linear functions of (t, \vec{x})
- ③ for any choice of t, \vec{x} , $(ct')^2 - (z')^2 = (ct)^2 - z^2$

The constancy of the speed of light is the statement that

$$(x')^2 + (y')^2 + (z')^2 - (ct')^2 = 0 \Leftrightarrow x^2 + y^2 + z^2 - (ct)^2 = 0$$

Assumption ③ is a little stronger; basically it fixes the overall scale of the linear relation we are looking for.

To implement this, write $x^0 = ct$, $x^{0'} = ct'$, so that we put time intervals in units of meters. Then the general linear relation between (x^0, \vec{x}^3) and $(x^{0'}, \vec{x}^{3'})$ is:

$$(z = x^3) \qquad (z' = x^{3'})$$

$$x^{0'} = Ax^0 - Bx^3$$

$$x^{3'} = -Cx^0 + Dx^3$$

then

$$(x^{0'})^2 - (x^{3'})^2 = (A^2 - C^2)(x^0)^2 - (D^2 - B^2)(x^3)^2 + (-2AB + 2CD)x^0x^3$$

this = $(x^0)^2 - (x^3)^2$ for all possible (x^0, x^3) if

$$A^2 - C^2 = 1, \quad D^2 - B^2 = 1 \quad \underline{\text{and}} \quad \frac{C}{A} = \frac{B}{D}$$

We have three equations for four unknowns, so there will be one free parameter. The first two equations are solved by using

$$A = \cosh \eta \quad C = \sinh \eta \quad \text{for some hyperbolic angle } \eta$$

$$D = \cosh \zeta \quad B = \sinh \zeta$$

The last equation implies $\tanh \eta = \tanh \zeta \Rightarrow \eta = \zeta$

Now define β by

$$\beta = \tanh \eta = \frac{\sinh \eta}{\cosh \eta}$$

Then

$$\cosh \eta = \frac{1}{\sqrt{1-\beta^2}} \equiv \gamma \quad \sinh \eta = \frac{\beta}{\sqrt{1-\beta^2}} = \beta\gamma$$

The final form of the transformation is:

$$x^{0'} = \gamma(x^0 - \beta x^3)$$

$$x^{3'} = \gamma(x^3 - \beta x^0)$$

$$\gamma = \frac{1}{\sqrt{1-\beta^2}}$$

Solving for x^0, x^3 :

$$x^0 = \gamma(x^{0'} + \beta x^{3'})$$

$$x^3 = \gamma(x^{3'} + \beta x^{0'})$$

Let's now try to interpret these equations by looking at some special cases. First, look at the locus of the origin of coordinates of F' as a function of time

$$x^{3'} = 0 \Rightarrow x^3 - \beta x^0 = 0$$

$$x^3 - (\beta c)t = 0$$

so this point moves in F in the $+z$ direction a velocity $v = \beta c$. Thus,

$$\beta = \frac{v}{c} \quad \gamma = \frac{1}{\sqrt{1 - v^2/c^2}}$$

Next, consider a clock at rest at a fixed value of $x^{3'}$, say $x^{3'} = 0$. Then, if $t=0$ and $t'=0$ coincide,

$$x^0 = \gamma x^{0'} \quad \text{or} \quad t = \frac{t'}{\sqrt{1 - v^2/c^2}}$$

so t' , the time read on the clock in F' , is smaller than t , the time elapsed in F , by a factor $\sqrt{1 - v^2/c^2}$. Similarly,

at a fixed value of x^3 , say $x^3 = 0$,

$$x^{0'} = \gamma x^0 \quad \text{or} \quad t' = \frac{t}{\sqrt{1-v^2/c^2}}$$

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so each observer thinks that the other's clocks run slow by the required time dilatation factor.

Next, let F put a stick of length L along the \hat{z} or $\hat{3}$ axis. The ends of the stick are at

$$(x^0, x^3) = (ct, 0) \quad x^0, x^3 = (ct, L)$$

Since the stick is moving in F' 's frame, he must locate the ends simultaneously if one end is at

$$(x^{0'}, x^{3'}) = (0, 0)$$

the other will be at $(x^{0'}, x^{3'}) = (0, L')$ Then

$$x^3 = L = \gamma(L' + \beta \cdot 0)$$

$$\text{or} \quad L' = \left(\frac{1}{\gamma}\right)L = \sqrt{1-v^2/c^2} L$$

F' sees this stick as contracted. F sees the same effect for a stick at rest with respect to F' . Finally, look at the equation

$$x^{0'} = \gamma(x^0 - \beta x^3)$$

$$\text{or} \quad t' = \frac{1}{\sqrt{1-v^2/c^2}} \left(t - \frac{v}{c^2} x^3 \right)$$

For events which occur at the same t , they are earlier in t' the further ahead they are. So our general analysis verifies all of the observations made in the previous lecture.

The transform from (x^0, x^3) to $(x^{0'}, x^{3'})$ is called a Lorentz transformation or, more simply, a boost. The result of two successive boosts is a boost: If

$$\begin{aligned} x^{0'} &= \gamma (x^0 - \beta x^3) & x^{0''} &= \gamma' (x^{0'} - \beta' x^{3'}) \\ x^{3'} &= \gamma (x^3 - \beta x^0) & x^{3''} &= \gamma' (x^{3'} - \beta' x^{0'}) \end{aligned}$$

then

$$\begin{aligned} x^{0''} &= \Gamma (x^0 - B x^3) \\ x^{3''} &= \Gamma (x^3 - B x^0) \end{aligned}$$

where: $\Gamma = \gamma' \gamma (1 + \beta \beta')$ $B = \frac{\beta + \beta'}{1 + \beta \beta'}$

Interpreting $B = V/c$, where V is the velocity of the composite boost

$$V = \frac{v + v'}{1 + vv'/c^2}$$

all one can show that $\Gamma = \frac{1}{\sqrt{1 - V^2/c^2}}$.

Notice that it is not possible, by composing boosts, to obtain

a velocity faster than c ! If we go back to

$$\beta = \tanh \eta \quad \gamma = \cosh \eta$$

the composite of two boosts yields

$$I = \cosh \eta \cosh \eta' + \sinh \eta \sinh \eta' = \cosh(\eta + \eta')$$

$$IB = \cosh \eta \sinh \eta' + \sinh \eta \cosh \eta' = \sinh(\eta + \eta')$$

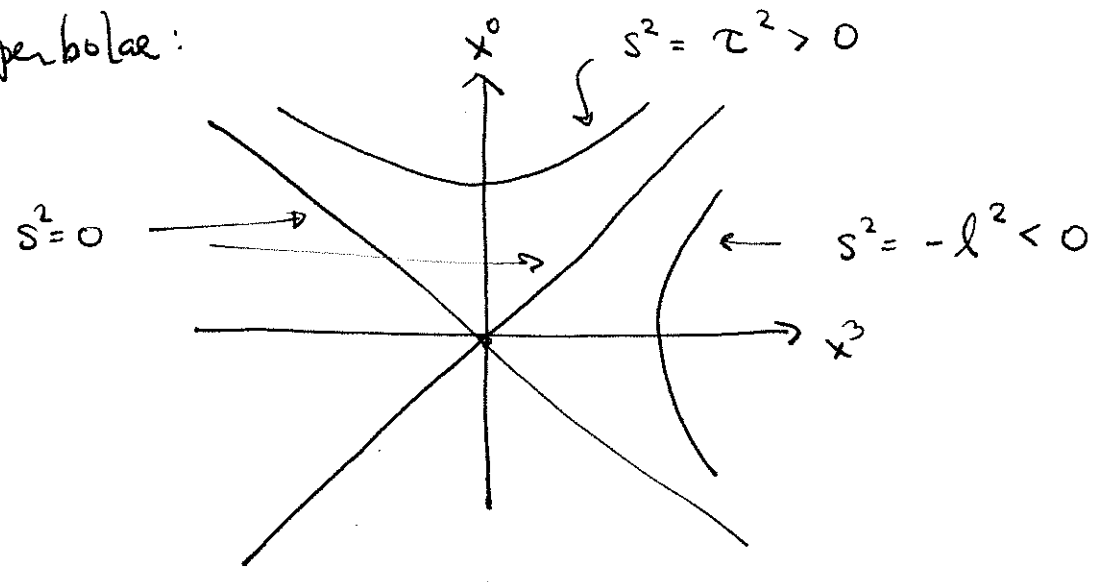
so the hyperbolic angles η just add. The useful angle η is called the rapidity of the boost.

Let's look at these relations more geometrically.

In the x^0, x^3 plane, the curves of constant

$$s^2 = (x^0)^2 - (x^3)^2$$

are hyperbolae:



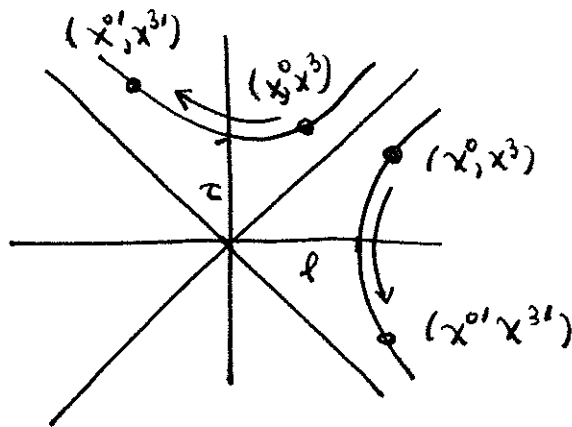
The quantity s^2 is called the interval. If $s^2 > 0$, we say that the interval (between (x^0, x^3) and $(0, 0)$) is time-like. The value $\tau = \sqrt{s^2}$ is the time that

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 elapses on a clock in the frame where $x^{3'} = 0$. This is called the "proper time" of the interval.

If $s^2 < 0$, we say that the interval is space-like. The value $l^2 = \sqrt{-s^2}$ is the length of the interval in the frame where $x^{0'} = 0$. This is called the "proper length" of the interval.

If $s^2 = 0$, we say that the interval is light-like. Then $x^0 = x^3$ or $x^3 = ct$ and the interval can be spanned by a light ray.

A boost preserves the value of s^2 and thus moves (x^0, x^3) to another point $(x^{0'}, x^{3'})$ on the same hyperbola



Notice that, if the interval between $(0,0)$ and $(x^0, x^3) = x$ is spacelike, the vector from $(0,0)$ to x goes forward in time in some frames and backwards in time in other frames.

Now generalize to

$$x = (x^0, x^1, x^2, x^3) = (ct, x, y, z)$$

A more general boost which relates coordinates x in a frame F to coordinates x' in a frame F' , moving at velocity \vec{v} with respect to F , is

$$x^{0'} = \gamma (x^0 - \frac{\vec{v}}{c} \cdot \vec{x})$$

$$\hat{v} \cdot \vec{x}' = \gamma (\hat{v} \cdot \vec{x} - |\frac{\vec{v}}{c}| x^0)$$

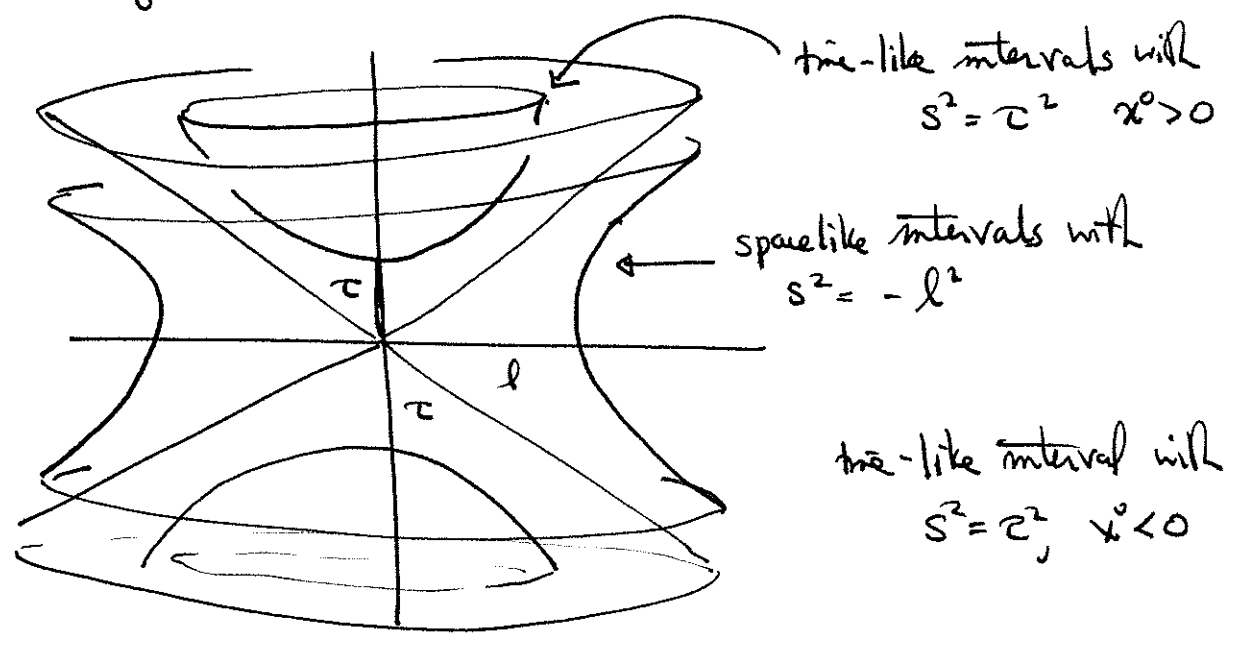
$$\gamma = \frac{1}{\sqrt{1 - v^2/c^2}}$$

$$\Rightarrow (\vec{x}')_{\perp} = (\vec{x})_{\perp} \quad \text{for components perpendicular to } \vec{v}$$

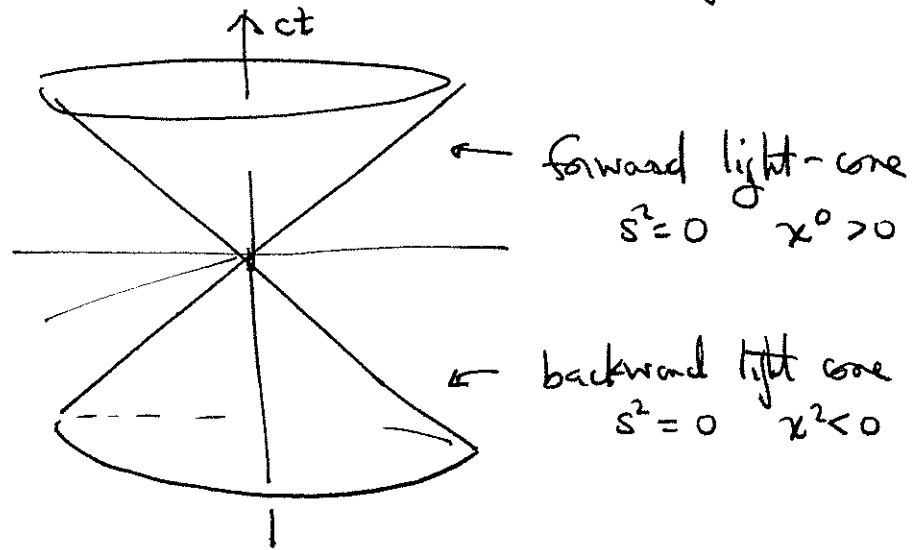
these transformations preserve the interval

$$s^2 = (ct)^2 - (x^1)^2 - (x^2)^2 - (x^3)^2$$

The surfaces of constant s^2 are hyperboloids:



The time-like and space-like regions are separated by two cones, the forward and backward light-cones.



Points inside the forward light-cone are definitely in the future of $(0,0)$. Points inside the backward light-cone are definitely in the past of $(0,0)$. For points x outside the light-cones, the time relation between x and $(0,0)$ is ambiguous, depends on the frame.

The linear transformations of (x^0, x^1, x^2, x^3) that preserve S are:

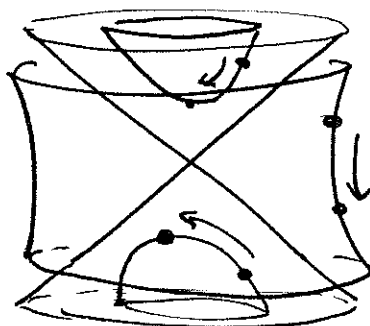
- ① boosts, parametrized by a velocity \vec{v}
- ② rotations of (x^1, x^2, x^3) , parametrized by an angle α .
- ③ any transformation that can be built as a product of boosts and rotations.

These transformations form a 6-parameter group of transformations

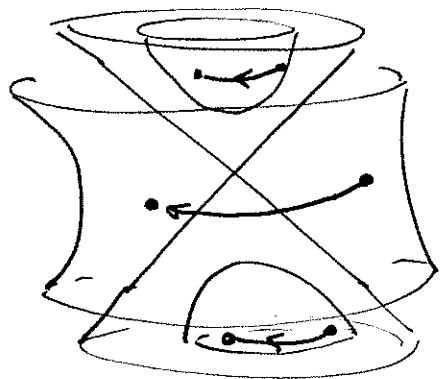
called the Lorentz group.

Typical Lorentz group transformations are:

boost:



rotation:



notice that the surface $s^2 = -l^2$ has only one connected piece; any point on the surface is connected to any other point by a continuous Lorentz transformation. However, the surface $s^2 = c^2 \geq 0$ splits into two disconnected parts \Rightarrow the future and past hyperboloids.