

## Gun3P Top-Level Commands

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## DCGunProblem

DCGunProblem:

```
{  
  RunId: test  
  SymmetryFactor: 1  
  //JustGenerateTreecotree: On  
  ElectricAbsoluteTolerance: 0.  
  ElectricRelativeTolerance: 1.00e-12  
  ElectricAbsoluteTolerance2: 0.  
  ElectricRelativeTolerance2: 1.00e-12  
  MagneticAbsoluteTolerance: 0.  
  MagneticRelativeTolerance: 1.00e-12  
  MaxIterations: 32  
  // FirstIterationForMagnetostaticProblem: 1  
  Save iteration data: On  
}
```

**DCGunProblem** specifies the problem symmetry, and tolerances needed to be satisfied in order for the iterative algorithm to converge.

**RunId** name of the run

**SymmetryFactor** symmetry of the problem. 1 for full 3D, 2 for half, 4 for quarter symmetry

**JustGenerateTreecotree** turn this option on to generate edge trees, run on 1 core only. This does not create the output directory but only generates the Magnetostatic co Tree. Needed to use it if the problem does not converge.

**ElectricAbsoluteTolerance**: Absolute error always set to 0

**ElectricRelativeTolerance**: Relative error between consecutive iterations in the E field when magnetic solver is not activated

**ElectricAbsoluteTolerance2**: Absolute error always set to 0

**ElectricRelativeTolerance2:** Relative error between consecutive iterations in the E field when magnetic solver is activated

**MagneticAbsoluteTolerance:** Absolute error always set to 0

**MagneticRelativeTolerance:** Relative error between consecutive iterations in the H field

**MaxIterations:** Maximum number of iteration before the solver stops.

**FirstIterationForMagnetostaticProblem:** The number of iteration the magnetic solver needs to start

**Save iteration data:** Save data relevant to each iteration

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**ElectrostaticProblem**

ElectrostaticProblem:

{

AnodeBoundaryId: 12

MeshFile: dcgun.ncdf

BasisOrder: 2

CurvedSurfaces: on

Charge averaging factor: 0.1

VolumeMaterial:

{ Id: 1

MediumName: Vacuum

PhysicalParameter:

{ Name: Permittivity

ConstantValue: 1.

}

}

Write dofs to disk: on

Debug bd dofs mapping: Off

Debug matrix assembly: Off

Use reduced solver: On

Outputs:

{

//Matrices and vectors: On

//Dofs for tracker: Off

Dofs for vizualization: On

//Dofs diff for vizualization: On

ElectrostaticFieldToken : On

FileName: test.data

```
Nx: 40
Ny: 50
Nz: 60

}

Boundary:
{ Id: 1
  ConditionType: Dirichlet
  DirichletValue: 0.

}

Boundary:
{
  Id: 2
  ConditionType: Dirichlet
  DirichletValue: -500.

}

Boundary:
{
  Id: 3
  ConditionType: Neumann
  NeumannValue: 0.

}

Compute non zero initial guess: On

LinearSolver:
{
  Solver: CG
  Preconditioner: CHOLESKY
  PrintFrequency: 50
  QuietMode: 0
  AbsoluteTolerance: 1.00e-99
  Tolerance: 1.00e-16
```

```
    MaxIterations: 5000
}
}
```

**ElectrostaticProblem** defines the electrostatic problem, mesh file, solver and boundary conditions

**AnodeBoundaryId** boundary surface ID of the Anode as defined from cubit

**MeshFile** mesh file generated by acdtool with format .ncdf

**BasisOrder** The order of the finite elements used in the simulation. Order 1-6 have been implemented. The higher the order is, the more accurate the calculation is and the more computational resources are for a fixed mesh. For most applications, using 2nd order is good enough to obtain the solution accuracy.

**CurvedSurfaces** on or off

The surfaces of the finite elements on the model surface are represented by curved surfaces to better approximate the geometry. If no specified, curved surfaces are used. off: The surfaces of the finite elements on the model surface are represented by flat surfaces.

**Charge averaging factor:** average value of the charge from one iteration to the next according to the formula

$$\text{NewRays} = (1 - \text{Charge averaging factor}) \times \text{PreviousRays} + \text{Charge averaging factor} \times \text{NewRays}$$

**VolumeMaterial** definite the electrical properties of the model

- **Id** block ID from cubit
- **MediumName:** label for the material name
- **PhysicalParameter** contains material properties for this volume
- **Name** property of the medium
  - **Permittivity:** relative permittivity of the medium
  - Permeability: relative permeability of the medium
  - Sigma: bulk conductivity of the medium units S/m
  - **ConstantValue:** value of the above property.

```
}
```

**Write dofs to disk:** write electric fields

**Debug bd dofs mapping:** on or off. Allow debugging for advanced users. Default is off.

**Debug matrix assembly:** on or off. Allow debugging for advanced users. Default is off.

**Use reduced solver:** on or off. Reduce the number of DOFs. Default is on.

**Outputs:** defines output of the electrostatic solvers

- **Matrices and vectors:** Off
- **Dofs for tracker:** Off
- **Dofs for vizualization:** On
- **Dofs diff for vizualization:** Off
- **ElectrostaticFieldToken :** On or off. On allows to export the electrostatic field on a Cartesian (structured) grid to be used for Track3p.
- **FileName:** name of the file to be written
- **Nx:** number of points sampled along the x axis.
- **Ny:** number of points sampled along the y axis.
- **Nz:** number of points sampled along the z axis.

**Boundary:** definition of boundaries on the specified surfaces. Each boundary need a separate container.

- **Id:** surface ID as assigned in cubit
- **ConditionType:** Dirichlet or Nuemann.
- **DirichletValue:** value of the electric potential of the Dirichlet boundary
- **NuemannValue:** value of the magnetic potential of the Dirichlet boundary (usually 0)

**Compute non zero initial guess:** On or off. Enables non zero initial values in the 0th iteration of the electric field.

**LinearSolver** defines the solver for the electrostatic problem. Leave settings as is.

- **Solver:** CG for larger probmelsn  
MUMPSFLOAT for smaller problems
- **Preconditioner:** CHOLESKY
- **PrintFrequency:** 50
- **QuietMode:** 0
- **AbsoluteTolerance:** 1.00e-99
- **Tolerance:** 1.00e-16
- **MaxIterations:** 5000

}

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**MagnetostaticProblem**

MagnetostaticProblem:

{

  MeshFile: dcgun.ncdf

  BasisOrder: 2

  CurvedSurfaces: on

  Charge averaging factor: 0.1

  VolumeMaterial: {

    Id: 1

    MediumName: Vacuum

    PhysicalParameter: {

      Name: Permittivity

      ConstantValue: 1.

    }

}

  Write dofs to disk: on

  Debug bd dofs mapping: Off

  Debug matrix assembly: Off

  Use reduced solver: On

  Outputs: {

    Dofs for vizualization: On

  }

  Boundary: {

    Id: 1

    ConditionType: Dirichlet

    DirichletValue: 0.

  }

```
Boundary: {
  Id: 2
  ConditionType: Dirichlet
  DirichletValue : 0
}
```

```
Compute non zero initial guess: On
LinearSolver:
{
  Solver:      MUMPSFLOAT
  Preconditioner:  CHOLESKY
  PrintFrequency: 50
  QuietMode:    0
  AbsoluteTolerance: 1.00e-99
  Tolerance:    1.00e-16
  MaxIterations: 5000
}
}
```

**MagnetostaticProblem** defines the solver and boundary conditions for the magnetostatic solver. Follow the same syntax for the electrostatic problem.

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## Tracker

Tracker:

```
{  
  JobName: ./gun3p_results/OUTPUT  
  Particlefile: partpath  
  // For forward tracking  
  t: 6.0e-6  
  Generate output for vizualization: on  
  Print emission statistics: On  
  // For backward tracking  
  Backward:  
  { t: 6.0e-6  
    Generate output for vizualization: on }
```

Domain:

```
{  
  t0: 0.0  
  dt: 1.0e-12  
  Window_Vol: 0  
  MaxImpacts: 2  
  LowEnergy: 0.0  
  HighEnergy: 1.0e+99  
  InitialEnergy: 0.0  
  dt backward: 1.0e-12  
  Backward velocity pattern: 0  
  Minimum backward velocity factor: 0.01  
  Strategy for dt: 0  
  Emission Nx: 200 //600, 300
```

Emission Ny: 100. //200, 100

Emission Nz: 300. //600, 400

Tracking Nx: 200. //600, 300

Tracking Ny: 100. //200, 100

Tracking Nz: 300 //600, 400

Tracking box x min: -0.11

Tracking box y min: -0.04

Tracking box z min: -0.001

Tracking box x max: 0.11

Tracking box y max: 0.04

Tracking box z max: 0.18

}

Monitor:

{

Type: PlaneCrossingsVsT

Name: screen

Plane point: 0., 0., 0.15999

Plane normal: 0., 0., 1.

Compute densities: On

Max x for densities: 0.110

Max y for densities: 0.004

X number of densities: 11

Y number of densities: 80

}

MeshInterface:

{

Type: pd

Localizer:

{

```
Type: USS_Curve
}

}

Emitter:
{

Type: 6

BoundaryID: 1

t0: -1.0e-12

t1: 1.0e-12

N: 1.0e+0

M: 9.10938e-31

Q: -1.60218e-19

d: 0.1e-3

// 1: center

// 2: stochastic

Sample Type: 1

Child Langmuir:

{

Whole boundary is emitter: On

Use electric field direction for initial forward velocity: On

Strategy: 6

Use average J: On

Backward velocity factor: 0.66666667

Forward velocity factor: 1.

Min allowed distance: 0.01e-3

Max allowed distance: 5.00e-3

Given delta phi: 100.0

Max allowed emission distance wrt z axis: 1.000000

First inter cycle factor: 1.0.
```

```
Inter cycle averaging factor: 1.0.  
Max allowed total current: 1.35e+9  
Reference z for emission surface: 1.50e-3  
Particles per face: 5  
}  
}  
// HERE  
Material:  
{  
// 1: Reflector  
// 2: Absorber  
// 3: Secondary emitter  
// 4: Test surface  
// 5: SymmetryPlane  
BoundarySurfaceID: 1  
Type: 2  
}
```

```
Material:  
{  
BoundarySurfaceID: 2  
Type: 2  
}
```

**Tracker** defines the particle tracking algorithm and solver based on the calculated electric and magnetic field for each iteration.

**JobName** location of the output results. Make sure it's the same name used in the job submission batch file.

**Particlefile**: prefix name of the particle files

**T** final value of the time for forward particle tracking

**Generate output for visualization** on or off. Generates output values for forward particle trajectories.

**Print emission statistics:** on or off. write emission data in the output file.

**Backward** defines backward tracking

- **t** final value of the time for forward particle tracking
- **Generate output for visualization:** Generates output values for backward particle trajectories.

**Domain** tracking domain within the model

- **t0** initial time
- **dt**: time step
- **Window\_Vol**: 0
- **MaxImpacts**: 2
- **LowEnergy**: 0.0
- **HighEnergy**: 1.0e+99
- **InitialEnergy**: 0.0
- **dt backward**: 1.0e-12
- **Backward velocity pattern**: 0
- **Minimum backward velocity factor**: 0.01
- **Strategy for dt**: 0
- **Emission Nx**: number of emission points sampled along the x axis
- **Emission Ny**: number of emission points sampled along the y axis
- **Emission Nz**: number of emission points sampled along the z axis
- **Tracking Nx**: number of tracking points sampled along the x axis
- **Tracking Ny**: number of tracking points sampled along the y axis
- **Tracking Nz**: number of tracking points sampled along the z axis
- **Tracking box x min**: minimum value of the bounding box for tracking in x
- **Tracking box y min**: minimum value of the bounding box for tracking in y
- **Tracking box z min**: minimum value of the bounding box for tracking in z
- **Tracking box x max**: minimum value of the bounding box for tracking in x
- **Tracking box y max**: minimum value of the bounding box for tracking in y
- **Tracking box z max**: minimum value of the bounding box for tracking in z

**Monitor** defines the monitor at which the beam parameters are calculated

- **Type** type of monitor used
  - **PlaneCrossingsVsT** a single plane monitor for particles crossing
    - Name:** name of monitor
    - Plane point:** coordinate of the plane center

**Plane normal:** unit vector normal to the plane

**Compute densities:** On or off. Compute charge density

**Max x for densities:** maximum value along x to compute emittances

**Max y for densities:** maximum value along u to compute emittances

**X number of densities:** number of points to emittances along x

**Y number of densities:** number of points to emittances along y

- **PlanesCrossing** parallel planes monitor for particles crossing each plane

**Name:** name of monitor

**First plane point:** coordinate of the first plane center

**Common plane normal:** unit vector along the parallel planes

**Distance between first and last planes:** distance between first and last planes

**Number of planes:** number of planes

**MeshInterface** localizer interface. Keep as default.

**Emitter** contains all information about the emission model and boundaries for the tracker

- **Type type of emittion model**

- 1: Thermal cathode
- 2: MP emission mode
- 3: Injection mode
- 4: Test particle mode
- 5: Window MP emission mode
- 6: Child-Langmuir

For most gun problems we use Child-Langmuir space charge limited emission model.

- **BoundaryID** surface ID of the emitter surface(s) as assigned in cubit
- **t0**: initial time the tracker applies Lorentz force equation. Use as default.
- **t1**: final time the tracker applies Lorentz force equation. Use as default.
- **N**: number of unit particles in the macroparticle
- **M**: real mass of a unit particle
- **Q**: real charge of a unit particle
- **d**: radius of the macroparticle for space charge calculations
- **Sample Type**: 1 or 2
  - **1 emission from the center of the elements**
  - **2 emission stochastically across the elements**
- **Child Langmuir** set the emission parameters of the Child Langmuir model

- **Whole boundary is emitter:** On or off. Sets the whole boundary as emitter. Default is on.
- **Use electric field direction for initial forward velocity:** On
- **Strategy:** 6 //keep as default.
- **Use average J:** On //keep as default.
- **Backward velocity factor:** 0.66666667 //keep as default.
- **Forward velocity factor:** 1. //keep as default.
- **Min allowed distance:** 0.01e-3 //keep as default.
- **Max allowed distance:** 5.00e-3 //keep as default.
- **Given delta phi:** 100.0 //keep as default.
- **Max allowed emission distance wrt z axis:** 1.000000 //keep as default.
- **First inter cycle factor:** 1.0. //default is 0.5
- **Inter cycle averaging factor:** 1.0. //default is 0.5
- **Max allowed total current:** 1.35e+9
- **Reference z for emission surface:** this is the first point beyond the cathode at which the fields are calculated and updated on the mesh.
- **Particles per face:** 5. One can experiment with this number to obtain better convergence.

**Material** defines particle boundary conditions for the tracker

- **ID** surface ID as assigned in cubit
- **Type** type of surface boundary conditions for the particle
  - 1: Reflector
  - 2: Absorber
  - 3: Secondary emitter
  - 4: Test surface
  - 5: SymmetryPlane

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## **Gun3pOutputConverter**

**Gun3pOutputConverter** is a post processing tool to calculate the E and H fields for a specific iteration and also output the field on structured grid (when ElectrostaticFieldToken : On)

Syntax on Perlmtter:

*gun3pOutputConverter filename.gun3p e*

*gun3pOutputConverter filename.gun3p m*

The output .mod and .data files will be stored in \gun3p\_results\OUTPUT\E and \gun3p\_results\OUTPUT\M